

# Computational Approach to Riemann Surfaces

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with

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# Theta-functional solutions to the Kadomtsev-Petviashvili equation



$$3u_{yy} + \partial_x(6uu_x + u_{xxx} - 4u_t) = 0$$

weakly two-dimensional waves in shallow water

- almost periodic solutions in terms of theta functions on arbitrary compact Riemann surfaces (Krichever 1978)

$$u = 2\partial_x^2 \ln \Theta(\mathbf{U}x + \mathbf{V}y + \mathbf{W}t + \mathbf{D}) + 2c$$



- $\mathbf{D} \in \mathbb{R}^g$  arbitrary

- Riemann theta function

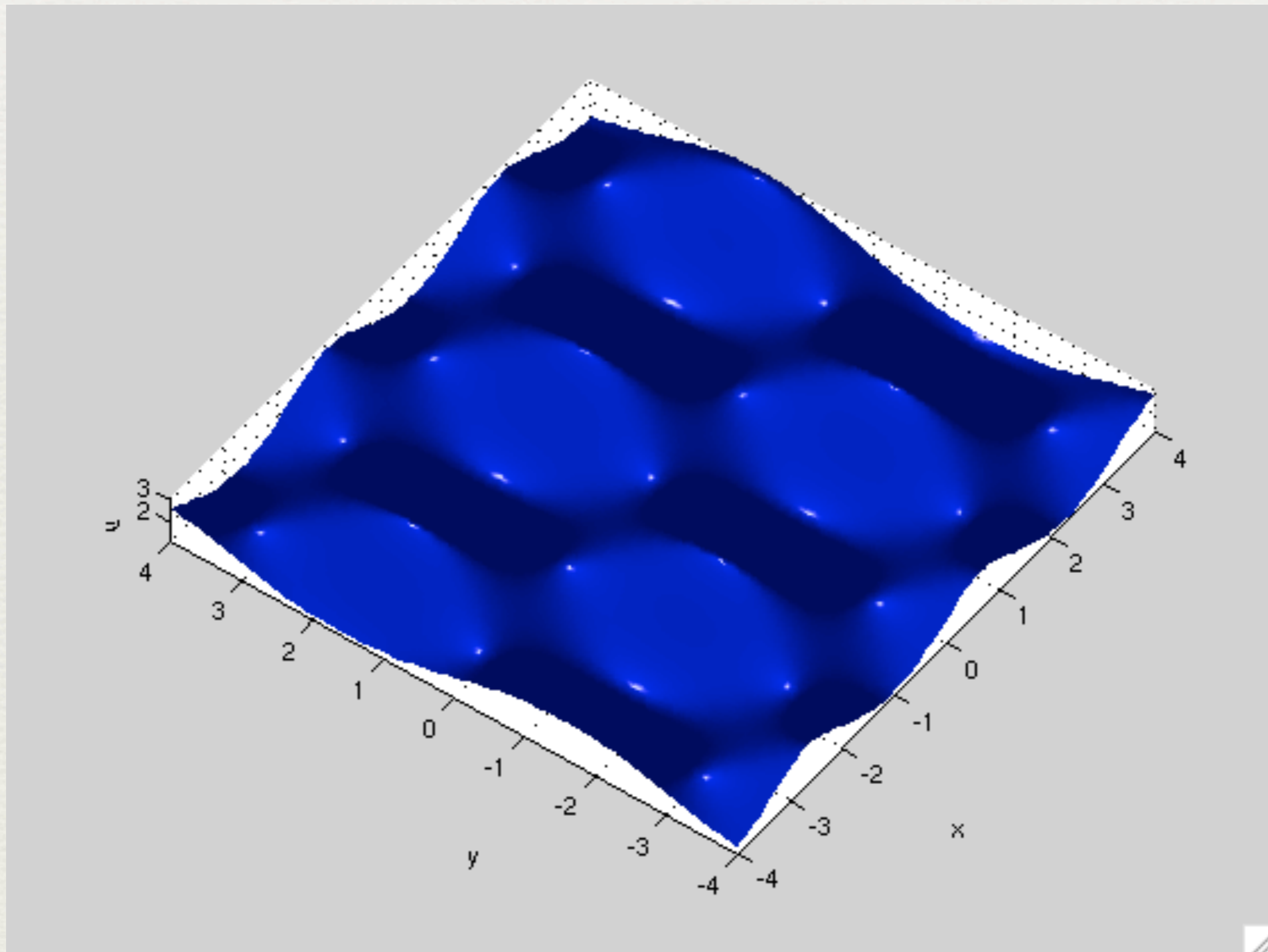
$$\Theta(\mathbf{x}|\mathbf{B}) = \sum_{\mathbf{n} \in \mathbb{Z}^g} \exp \{i\pi \langle \mathbf{B}\mathbf{n}, \mathbf{n} \rangle + 2\pi i \langle \mathbf{n}, \mathbf{x} \rangle\}$$

- $\mathbf{B}$  Riemann matrix, matrix of  $b$ -periods of the holomorphic differentials
- $\mathbf{U}, \mathbf{V}, \mathbf{W}$ , vectors expressible in terms of derivatives of the holomorphic differentials,  $c$  constant expressible in terms of theta functions



# Hyperelliptic solutions ( $g=2$ )

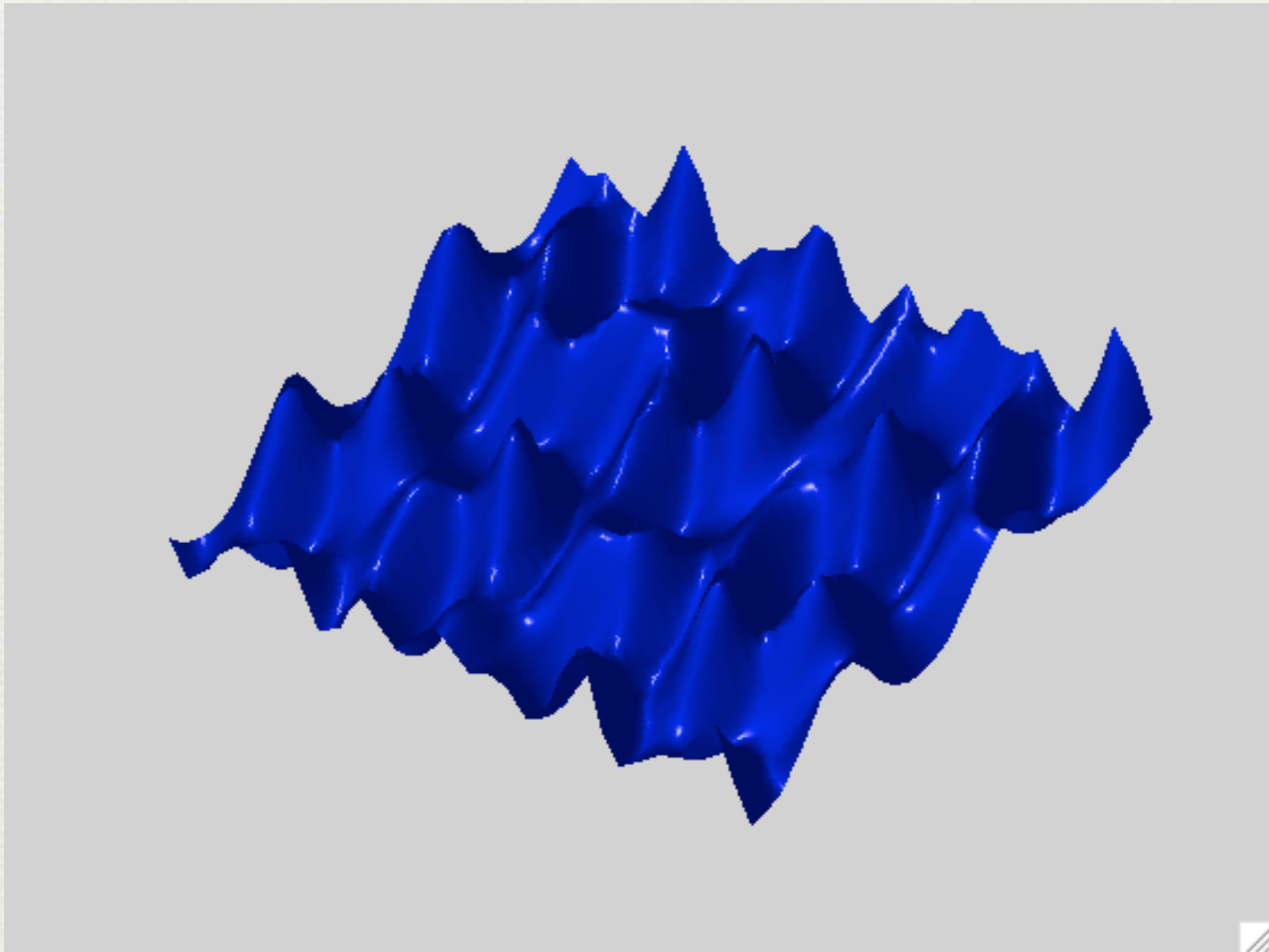
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# Hyperelliptic solution ( $g=4$ )

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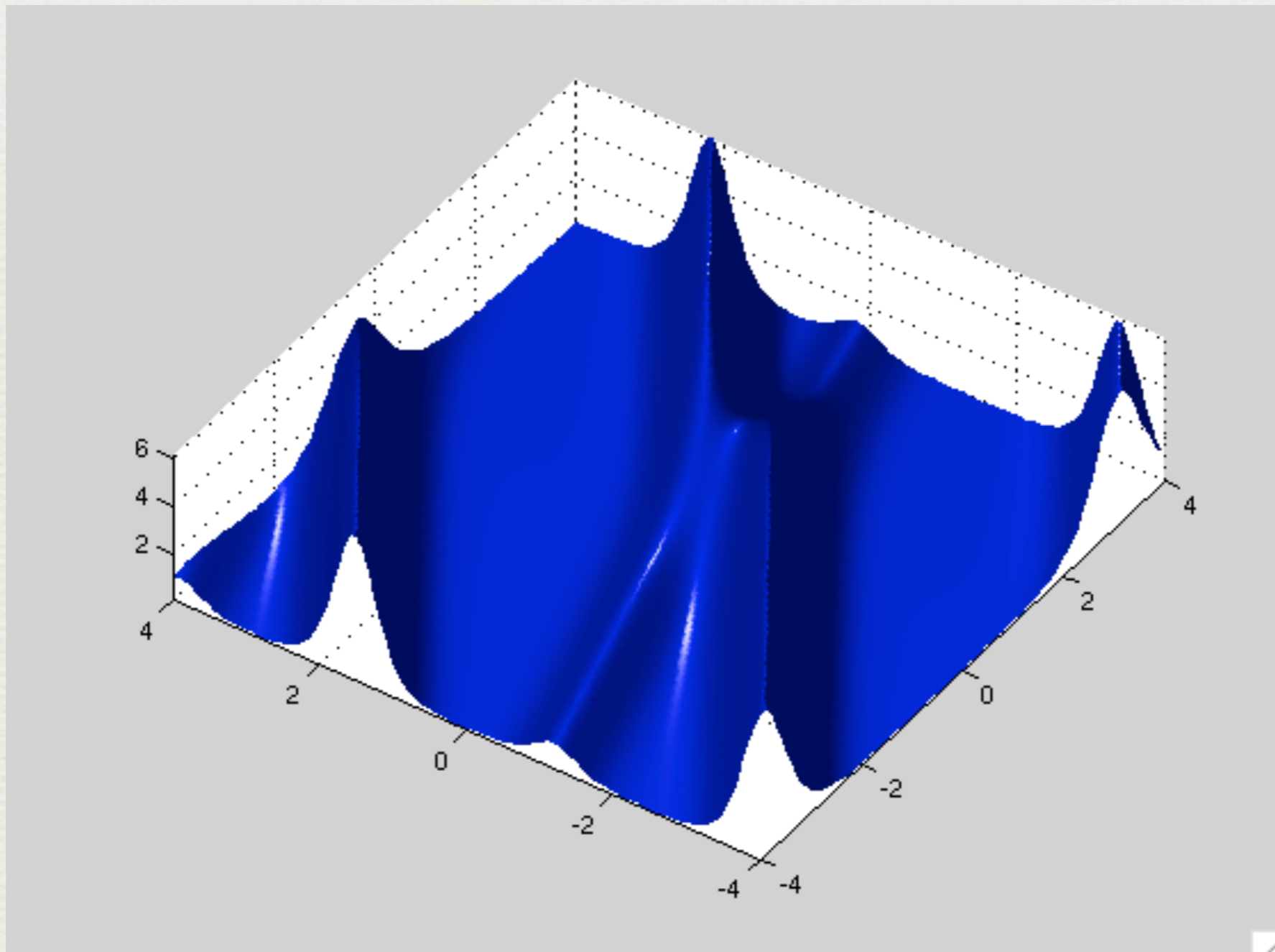
# (Line)Solitons (localized in one direction), 2-soliton

- ♦ branch points coincide pairwise, surface of genus 0 in the limit



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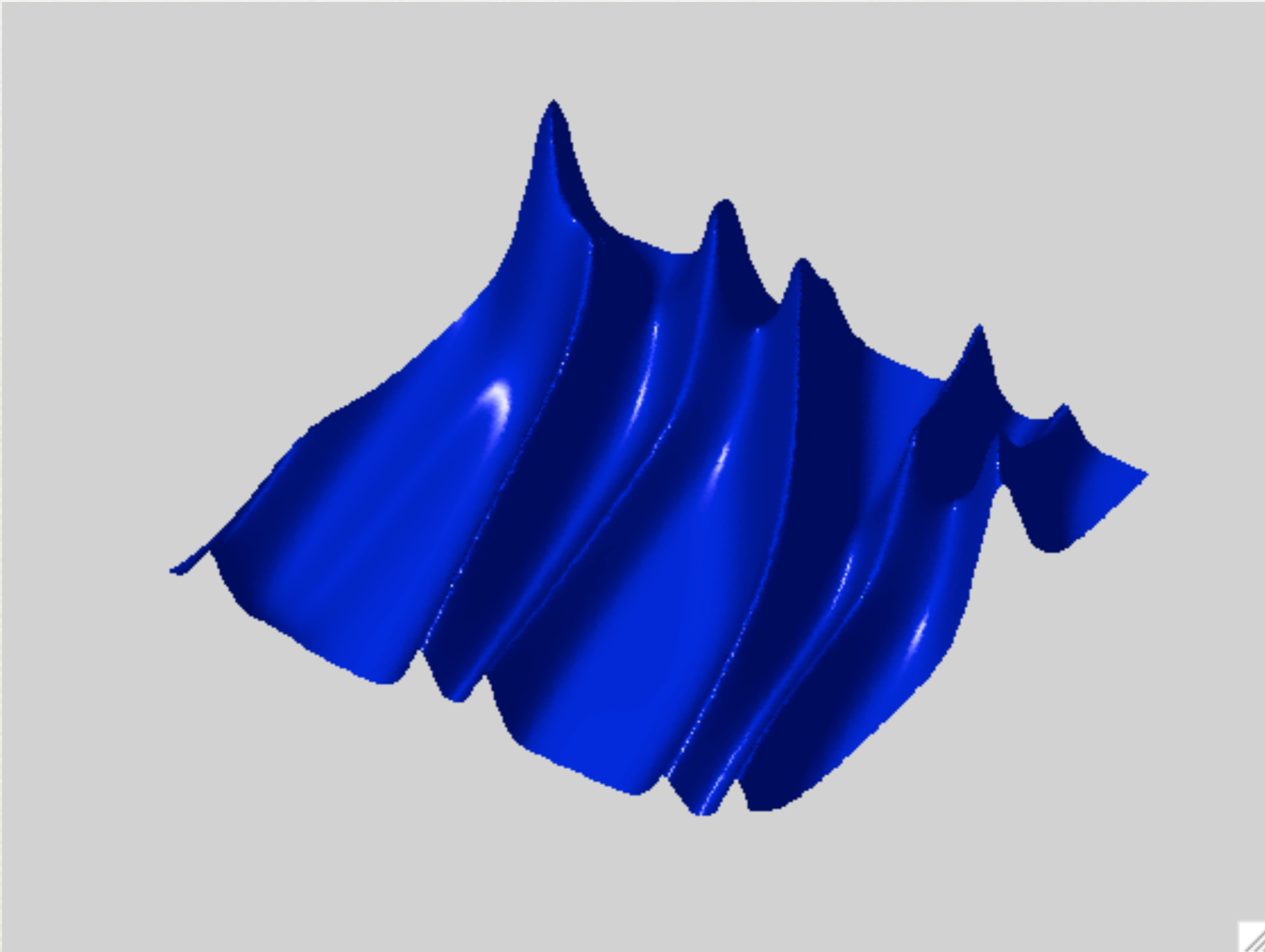




# (Line) Solitons, 4-soliton



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# Symbolic vs. numerical

- ♦ Deconinck, v. Hoeij, Patterson: *algcurves* package in Maple (2001)
- ♦ symbolic approach, exact expressions (e.g.  $\text{RootOf}(x^2-2)$ ) manipulated and numerically evaluated, in principle infinite precision
- ♦ Frauendiener, K.: fully numeric approach (*floating point*), hyperelliptic curves (1998), much more rapid, allows study of families of curves and of more complicated curves



# Outline

- ♦ Riemann surfaces and algebraic curves
- ♦ Branch points and singular points
- ♦ Monodromy and homology
- ♦ Puiseux expansions and holomorphic differentials
- ♦ Real Riemann surfaces
- ♦ Hyperelliptic surfaces
- ♦ Performance tests and examples



# Riemann surfaces

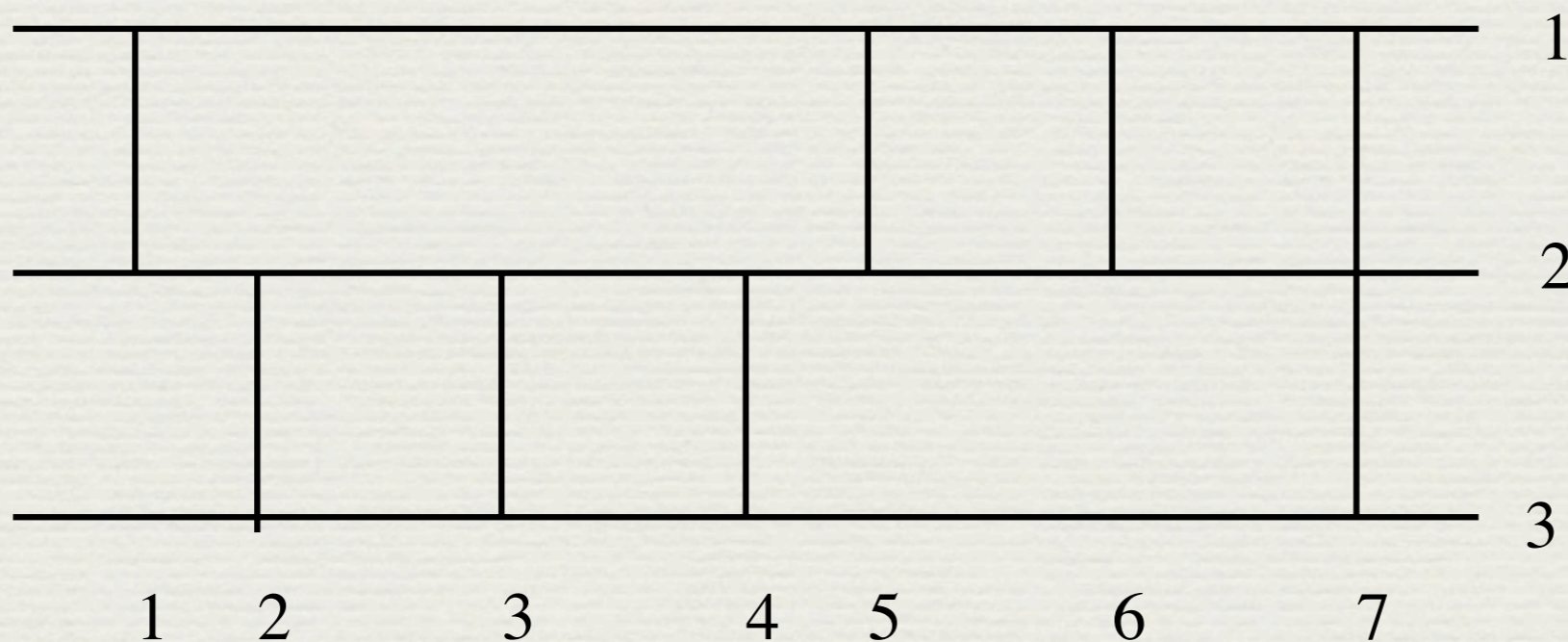
- ♦ Definition: A Riemann surface is a connected one-dimensional complex analytic manifold, i.e., a connected two-dimensional real manifold  $R$  with a complex structure  $\Sigma$  on it
- ♦ Theorem: All compact Riemann surfaces can be described as compactifications of non-singular algebraic curves



# Algebraic curves

- Definition: plane algebraic curve  $C$  subset in  $\mathbb{C}^2$ ,  
 $C = \{(x, y) \in \mathbb{C}^2 \mid f(x, y) = 0\}$ ,

$$f(x, y) = \sum_{i=0}^M \sum_{j=0}^N a_{ij} x^i y^j = \sum_{j=0}^N a_j(x) y^j$$

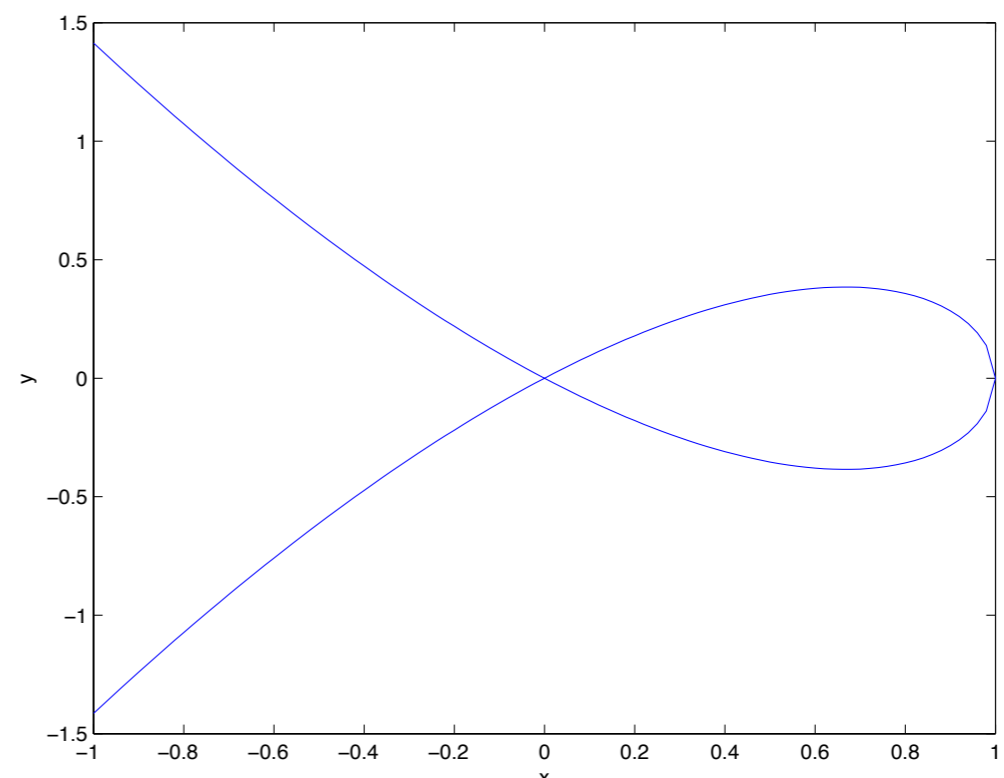




# Critical points

- general position:  $N$  distinct solutions  $y_n$  for given  $x$ ,  $N$  sheets of the Riemann surface
- Implicit function theorem: unique solution to  $f(x, y) = 0$  in vicinity of solution  $(x_0, y_0)$  if  $f_y(x_0, y_0) \neq 0$
- branch point:  $f(x_0, y_0) = f_y(x_0, y_0) = 0$ , but  $f_x(x_0, y_0) \neq 0$   
singular point:  $f(x_0, y_0) = f_y(x_0, y_0) = f_x(x_0, y_0) = 0$
- critical points given by the resultant  $R(x)$  of  $Nf - f_y y$  and  $f_y$

simple double point:  
$$y^2 + x^3 - x^2 = 0$$





# Resultant

- resultant of  $Nf - f_y y$  and  $f_y$ ,  $2N \times 2N$  Sylvester determinant

$$R(x) =$$

$$\begin{pmatrix} a_{N-1} & 2a_{N-2} & \dots & Na_0 & 0 & \dots & \dots & 0 \\ 0 & a_{N-1} & 2a_{N-2} & \dots & Na_0 & 0 & \dots & 0 \\ \vdots & \ddots & & & & & \ddots & \vdots \\ 0 & \dots & \dots & 0 & a_{N-1} & 2a_{N-2} & \dots & Na_0 \\ Na_{N-1} & (N-1)a_{N-2} & \dots & a_1 & 0 & \dots & \dots & 0 \\ 0 & Na_{N-1} & (N-1)a_{N-2} & \dots & a_1 & 0 & \dots & 0 \\ \vdots & \ddots & & & & & \ddots & \vdots \\ 0 & \dots & \dots & 0 & Na_{N-1} & (N-1)a_{N-2} & \dots & a_1 \end{pmatrix}$$



# Numerical root finding

- construct companion matrix (has  $R(x)$  as the characteristic polynomial), find eigenvalues with machine precision
- multiple zeros are not found with machine precision, ex.  $y^7 = x(x-1)^2$  Klein curve,  $R(x) = x^6(x-1)^{12}$ , `roots(R(x))` returns the following cluster of roots

```
1.1053 + 0.0297i
1.1053 - 0.0297i
1.0736 + 0.0790i
1.0736 - 0.0790i
1.0224 + 0.1032i
1.0224 - 0.1032i
0.9686 + 0.0980i
0.9686 - 0.0980i
0.9264 + 0.0686i
0.9264 - 0.0686i
0.9037 + 0.0245i
0.9037 - 0.0245i,
```



# polynomial root finding

- ♦ badly conditioned problem
- ♦ Zeng: *multroot package* for multiple roots  
(Newton iteration, minimize error by choice of multiplicity structure)
- ♦ resultant high order polynomial, therefore direct Newton iteration in  $x$  and  $y$ . Initial iterates from resultant with respect to  $x$  and  $y$ , pairing
- ♦ *endgame* for higher order zeros



# Singularities

- multiple roots are tested for vanishing  $f_x(x, y)$
- infinity: homogeneous coordinates  $X, Y, Z$   
via  $x = X/Z, y = Y/Z$

$$F(X, Y, Z) = Z^d f(X/Z, Y/Z) = 0$$

infinite points:  $Z = 0$ , finite points:  $Z = 1$

- Singular points at infinity:  
 $F_X(X, Y, 0) = F_Y(X, Y, 0) = F_Z(X, Y, 0) = 0$



# Example

- curve

$$f(x, y) = y^3 + 2x^3y - x^7 = 0,$$

- finite branch points

bpoints =

-0.3197 - 0.9839i

0.8370 - 0.6081i

-1.0346

0

0.8370 + 0.6081i

-0.3197 + 0.9839i

- singularities,

sing =	X	Y	Z	
	0	0	1	4
	0	1	0	9

corresponding to  $x = y = 0$  and  $Y = 1, X = Z = 0$

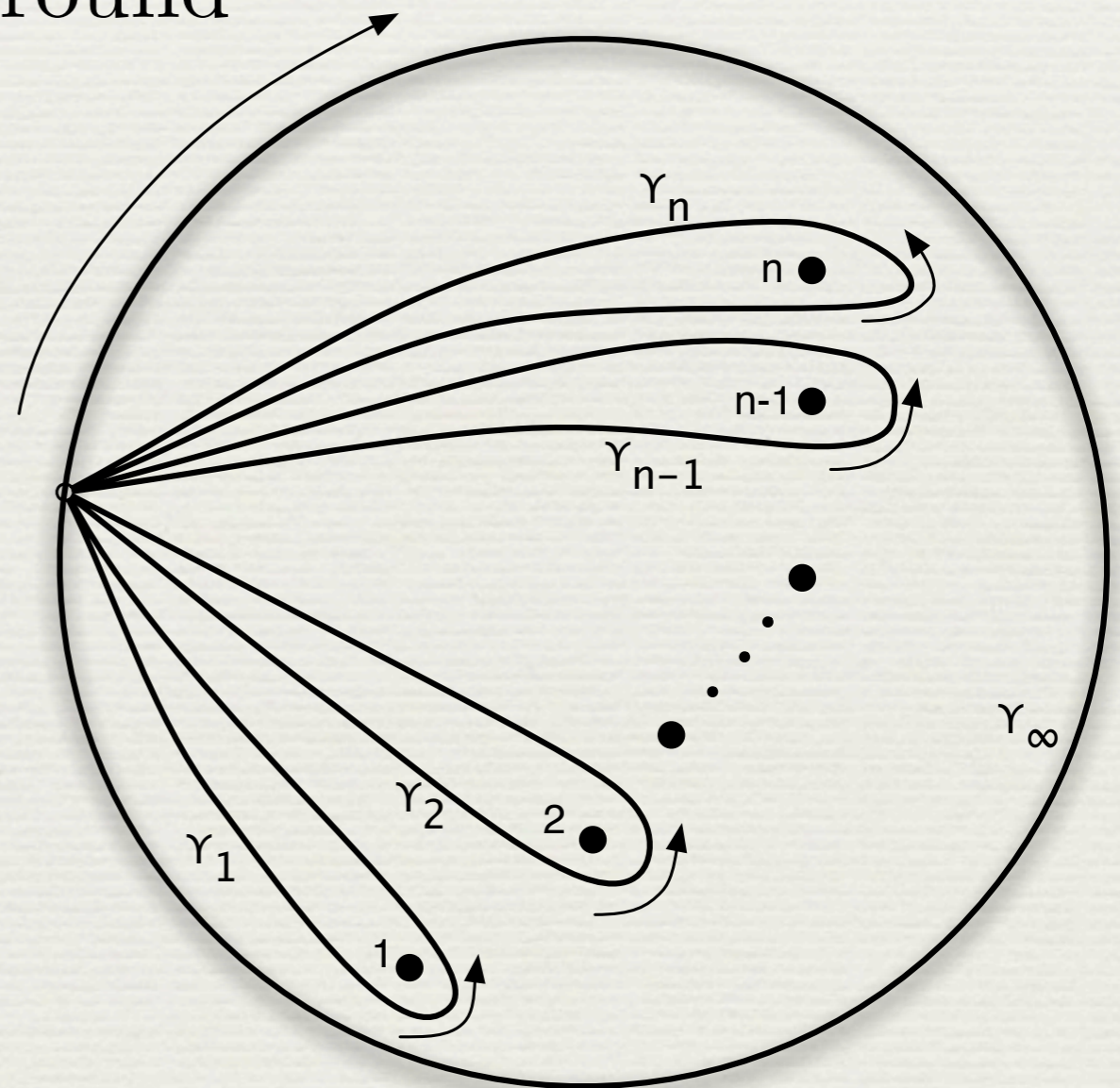


# Fundamental group

- branching structure at critical points, lift closed contours in the base around points  $b_1, \dots, b_n$  to the covering

- generators  $\{\gamma_k\}_{k=1}^n$  of fundamental group  $\pi_1(\mathbb{C}\mathbb{P}^1 \setminus \{b_1, \dots, b_n\})$

$$\gamma_1 \gamma_2 \cdots \gamma_n \gamma_\infty = \text{id}$$

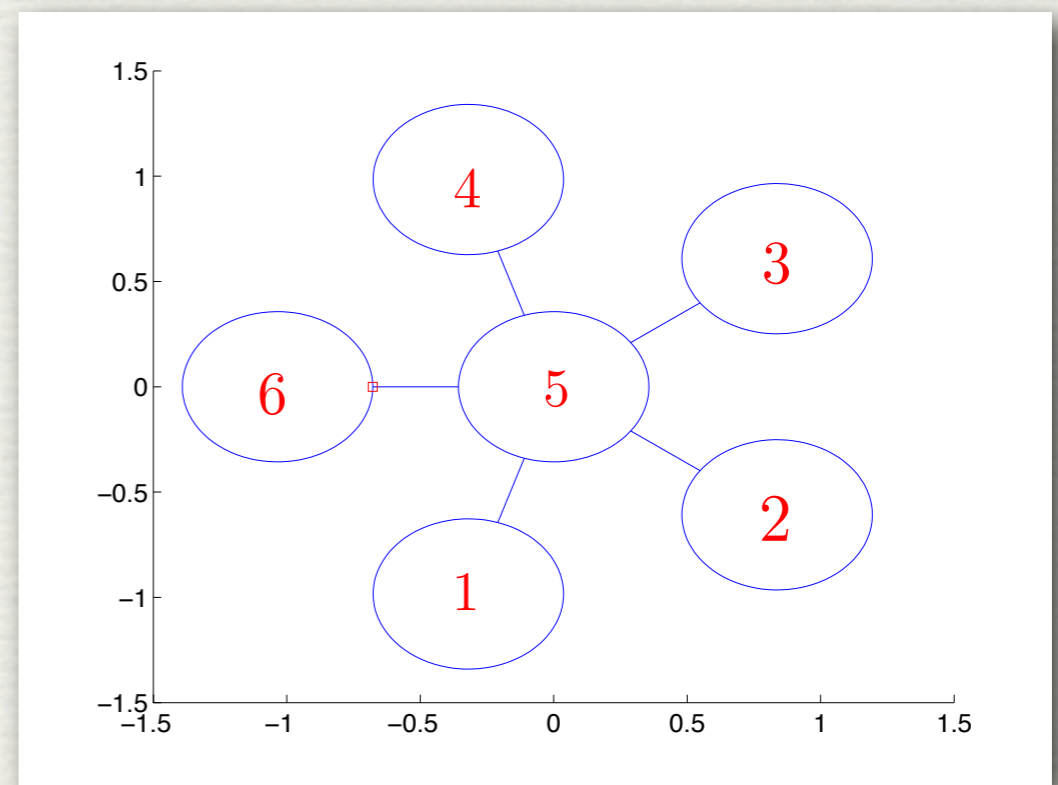
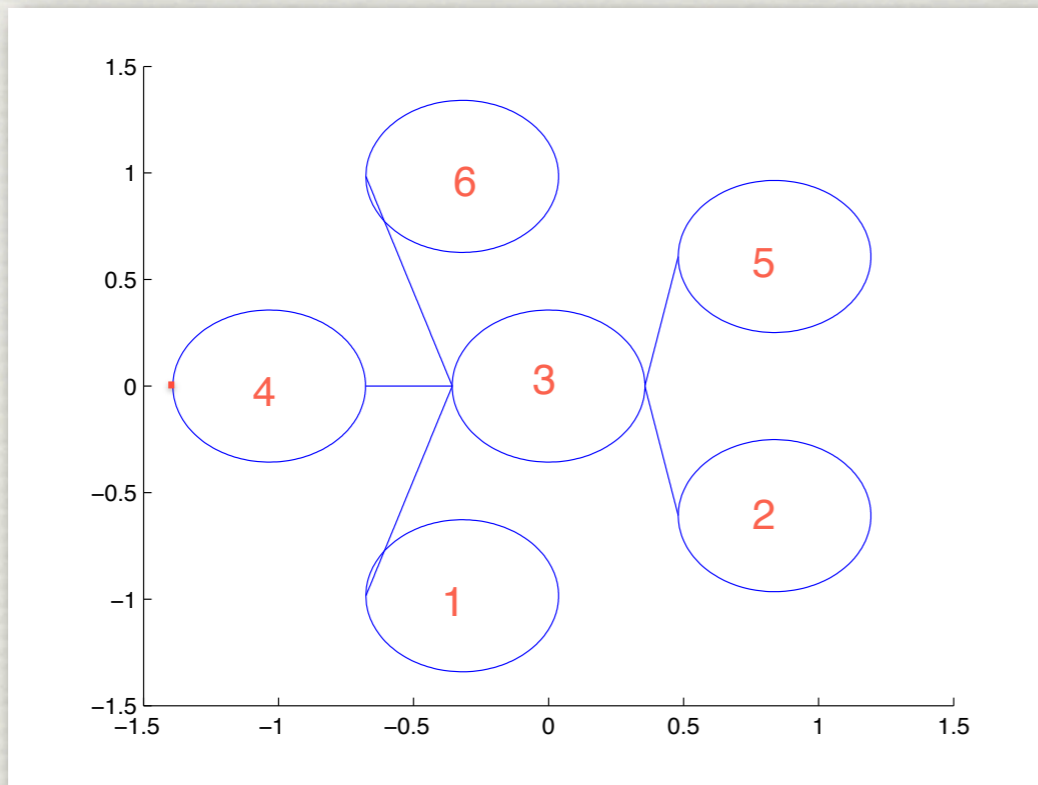




# Minimal spanning tree

- ◆ Maple: halfcircles around critical points, deformation of connecting paths
- ◆ shortest integration paths: start with critical point close to the base, choose point with minimal distance, iterate (Frauendiener, K, Shramchenko 2011)

◆ ex:





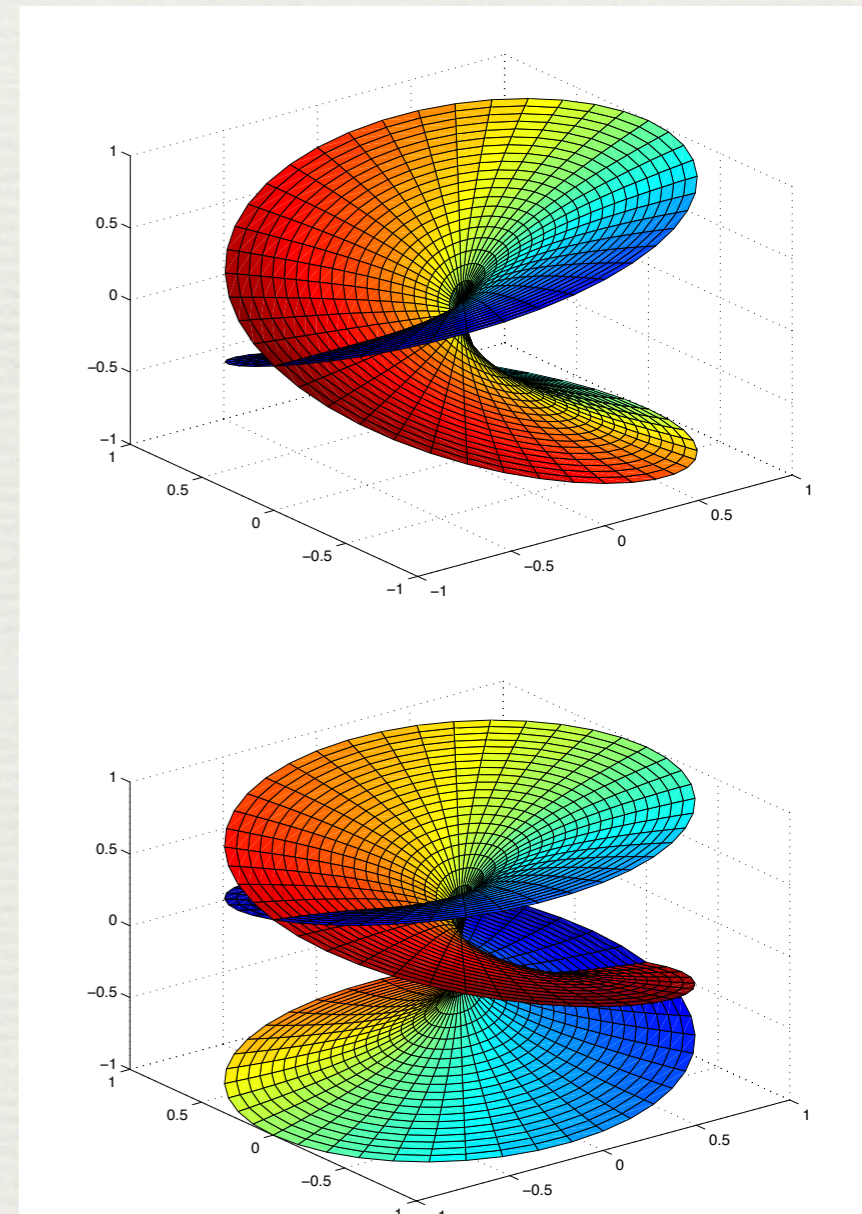
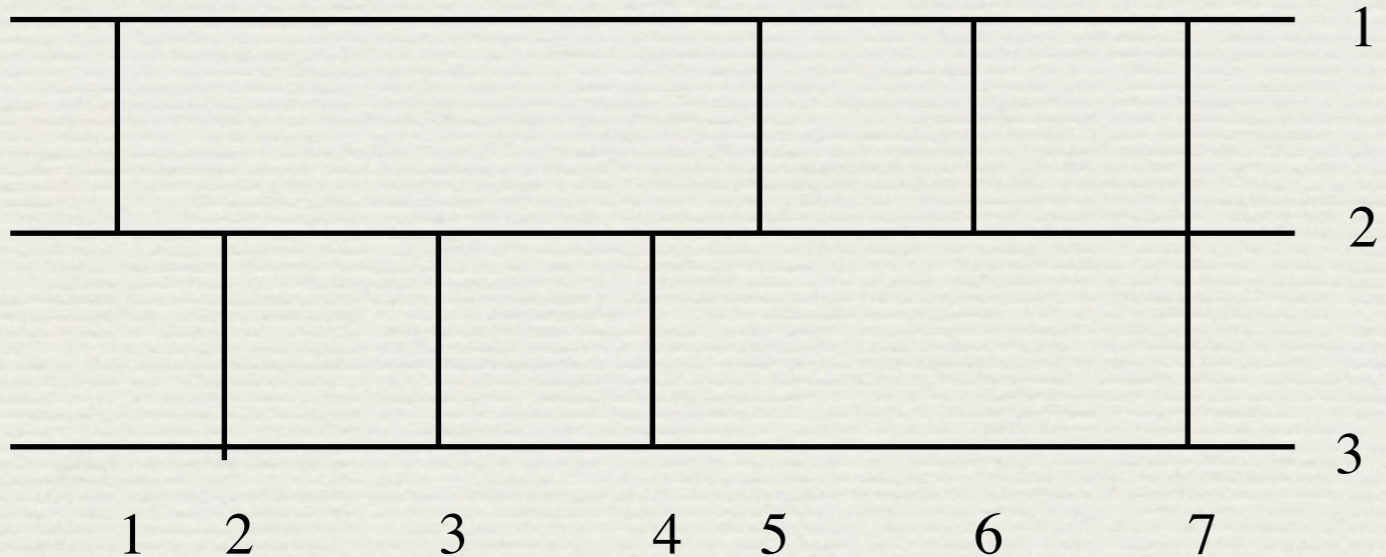
# Monodromies

- ♦ analytic continuation along a generator: sheets can change
- ♦ monodromy at infinity follows from condition on generators

• ex.:

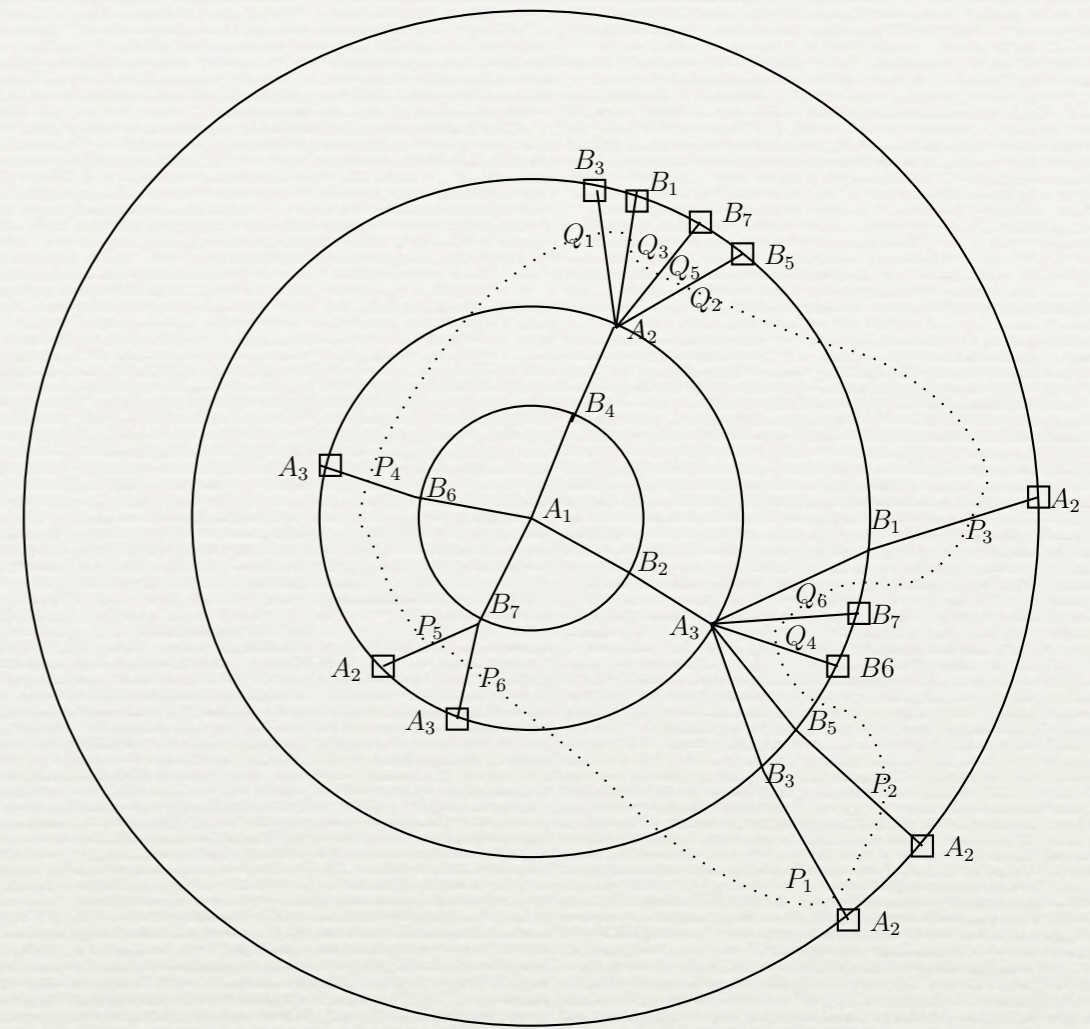
Mon =

2	1	1	1	2	2	2
1	3	3	3	1	1	3
3	2	2	2	3	3	1





# Homology



- ♦ Treutkoff-Treutkoff algorithm: Riemann surface connected, planar tree for given monodromies
- ♦  $2g+N-1$  closed contours built from the generators of the fundamental group, with known intersection numbers
- ♦ canonical basis of the homology:

$$a_i \circ b_j = -b_j \circ a_i = \delta_{ij} \quad i, j = 1, \dots, g$$



# Puiseux expansion

- desingularization: atlas of local coordinates to identify all sheets in the vicinity of the singularity
- $y^2 = x$ , no Taylor expansion  $y(x)$  near  $(0, 0)$ , Puiseux expansion

$$x = t^r, \quad y = \alpha_1 t^{s_1} + \dots$$

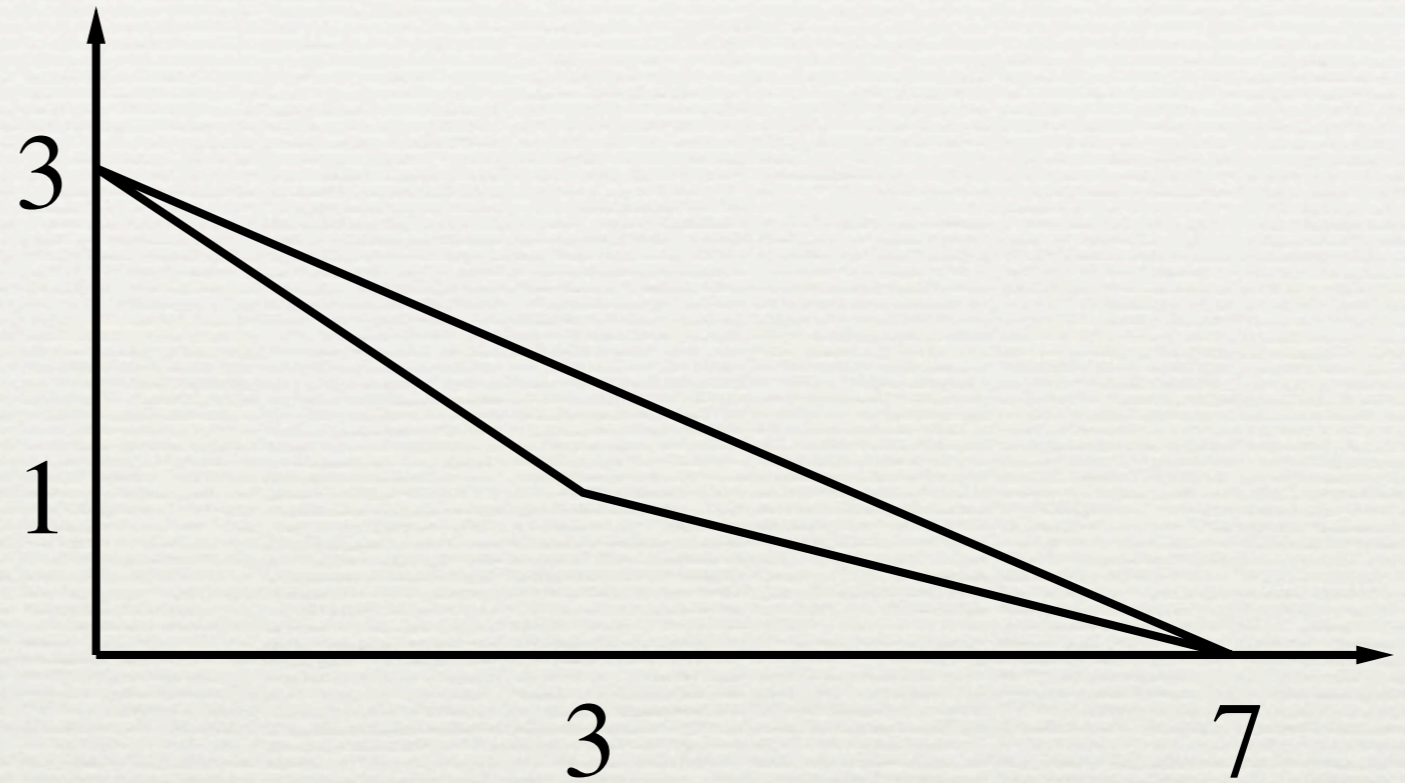
$$r, s_1, \dots \in \mathbb{N}, \quad \alpha_i \in \mathbb{C} \text{ for } i = 1, 2, \dots$$

- $y = 0$  zero of order  $m$  for  $f(0, y) = 0$ ,  $m$  inequivalent expansions needed to identify all sheets, *singular part*



# Newton polygon

- ex.:  $f(x, y) = y^3 + 2x^3y - x^7 = 0$



PuiExp{1} =

2.0000	3.0000	$0 + 1.4142i$
2.0000	3.0000	$0 - 1.4142i$
1.0000	4.0000	0.5000

PuiExp{2} =

4.0000	7.0000	-1.0000
4.0000	7.0000	$0 + 1.0000i$
4.0000	7.0000	$0 - 1.0000i$
4.0000	7.0000	1.0000

PuiExp{1} for  $(0, 0)$   $([0, 0, 1])$ , PuiExp{2} for infinity  $([0, 1, 0])$



# Holomorphic 1-forms

- holomorphic in each coordinate chart,  $g$ -dimensional space
- Noether:

$$\omega_k = \frac{P_k(x, y)}{f_y(x, y)} dx ,$$

adjoint polynomials  $P_k(x, y) = \sum_{i+j \leq d-3} c_{ij}^{(k)} x^i y^j$ ,  
degree at most  $d - 3$  in  $x$  and  $y$  ( $d = \max(i + j)$  for  $a_{ij} \neq 0$ )

- singular point  $P$ :  $\delta_P$  conditions via Puiseux expansions
- infinity: homogeneous coordinates
- ex.:  $f(x, y) = y^3 + 2x^3y - x^7 = 0$

$$\omega_1 = \frac{x^3}{3y^2 + 2x^3}, \quad \omega_2 = \frac{xy}{3y^2 + 2x^3}$$



# Cauchy integral approach

- numerical problem: cancellation errors, ex.  $\frac{e^x - 1}{x}$  for  $x \rightarrow 0$
- Cauchy formula

$$f(t) = \frac{1}{2\pi i} \int_{\gamma} \frac{f(t')}{t' - t} dt'$$

- closed contours around critical points identified via monodromy group
- series in  $t$  for holomorphic  $f$  ( $|t| < |t'|$ )

$$f(t) = \frac{1}{2\pi i} \sum_{n=0}^{\infty} t^n \int_{\gamma} f(t') \frac{dt'}{(t')^{n+1}}$$

- Puiseux series:  $f = y$ ;  
holomorphicity condition for differentials (no negative powers)
- infinity: express  $\gamma_{\infty}$  in terms of the  $\gamma_i$



# Numerical integration

- Gauss-Legendre integration: expansion of integrand in terms of Legendre polynomials  $\mathcal{F}(x_l) = \sum_{k=0}^{N_l} a_k \mathcal{P}_k(x_l)$ ,  $l = 0, \dots, N_l$

$$\int_{-1}^1 \mathcal{F}(x) dx \sim \sum_{k=0}^{N_l} a_k \int_{-1}^1 \mathcal{P}_k(x) dx$$

- integration:

$$\int_{-1}^1 \mathcal{F}(x) dx \sim \sum_{k=0}^{N_l} \mathcal{F}(x_k) \mathcal{L}_k$$

- analytic continuation of  $y_j$  along the  $\gamma_i$  on the collocation points  $x_l$ , integration of the holomorphic differentials



# Riemann matrix

- $a$ - and  $b$ -periods

$$\mathbf{B} = \mathcal{A}^{-1}\mathcal{B}$$

- numerical asymmetry of Riemann matrix as test
- ex.:

RieMat =

$$\begin{array}{cc} 0.3090 + 0.9511i & 0.5000 - 0.3633i \\ 0.5000 - 0.3633i & -0.3090 + 0.9511i. \end{array}$$



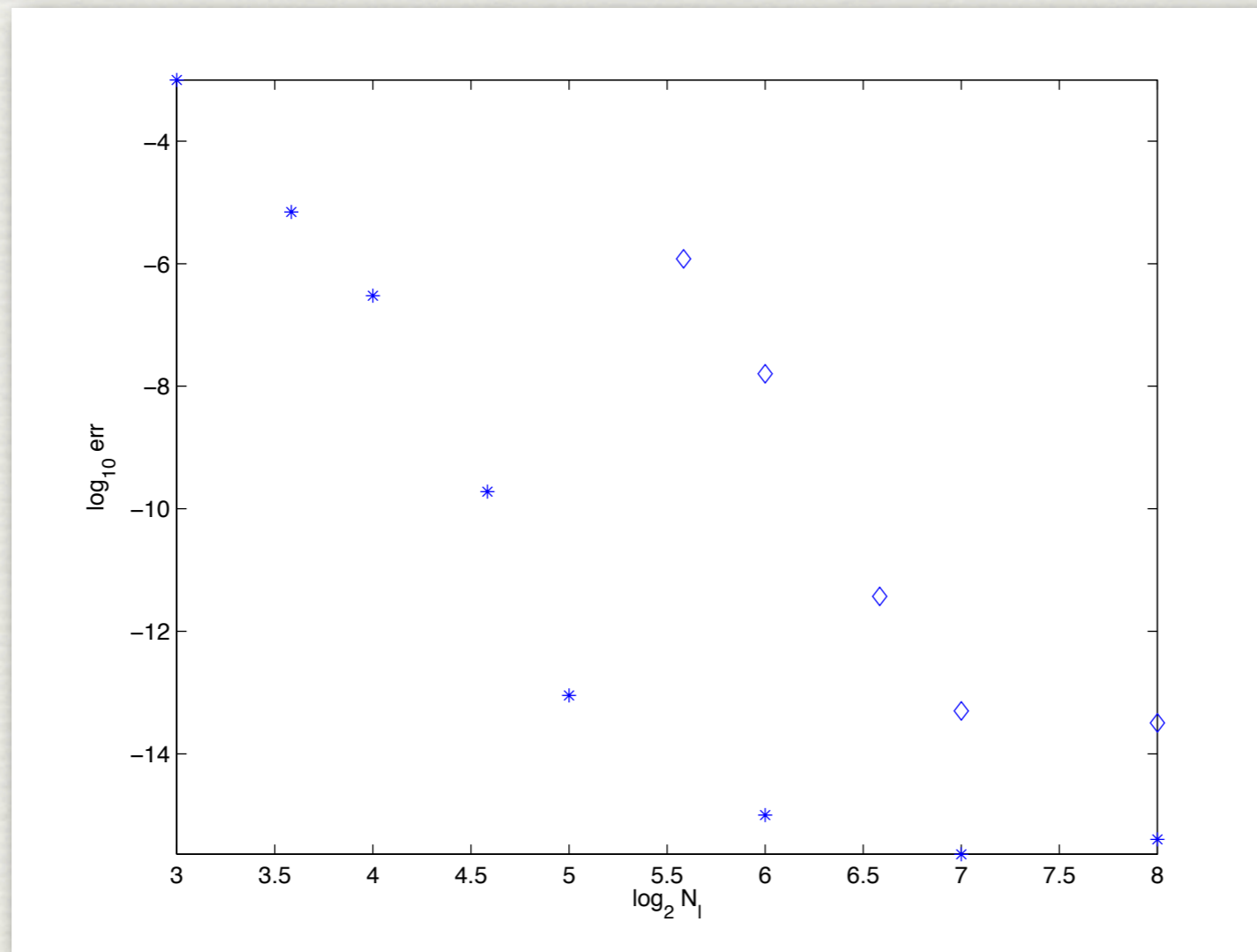
# Performance

- error: asymmetry of the Riemann matrix and periods of cycles homologous to 0 for

$$f(x, y) = y^3 + 2x^3y - x^7 = 0 \text{ (stars) and}$$

$$f(x, y) = y^9 + 2x^2y^6 + 2x^4y^3 + x^6 + y^2 = 0 \text{ (diamonds),}$$

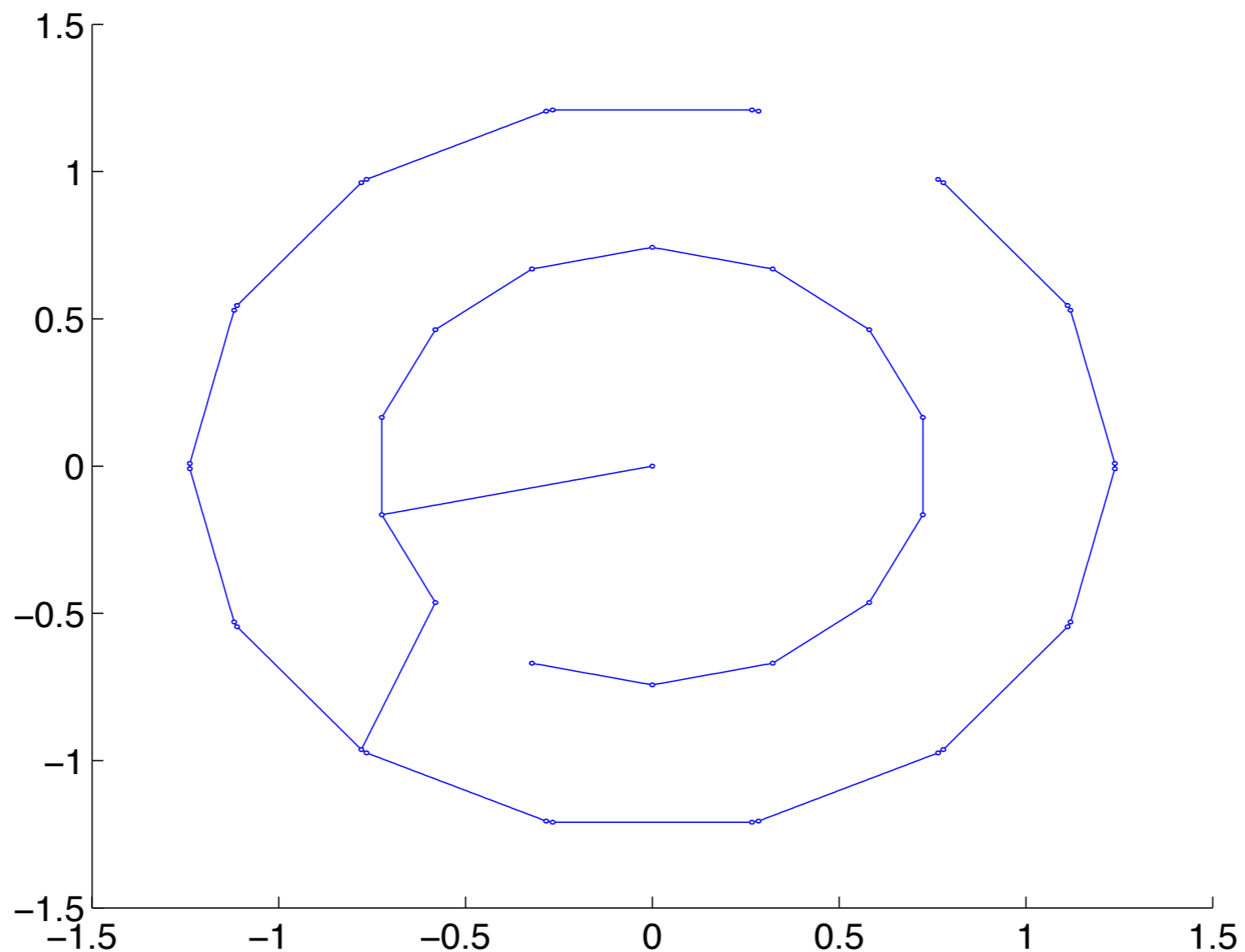
spectral convergence





- $$f(x, y) = y^9 + 2x^2y^6 + 2x^4y^3 + x^6 + y^2 = 0$$

genus 16, 42 finite branch points, two singular points  $(0, 0, 1)$  and  $(1, 0, 0)$ ,  
 minimal distance between branch points 0.018





# Theta functions

- theta series approximated as sum

$$\Theta(\mathbf{z}|\mathbf{B}) \approx \sum_{N_1=-N_\theta}^{N_\theta} \dots \sum_{N_g=-N_\theta}^{N_\theta} \exp \left\{ i\pi \langle \mathbf{B}\vec{N}, \vec{N} \rangle + 2\pi i \langle \vec{z}, \vec{N} \rangle \right\}$$

- use periodicity properties of theta function to have argument in the fundamental cell,  $\lambda_1$  smallest eigenvalue of the imaginary part of the Riemann matrix

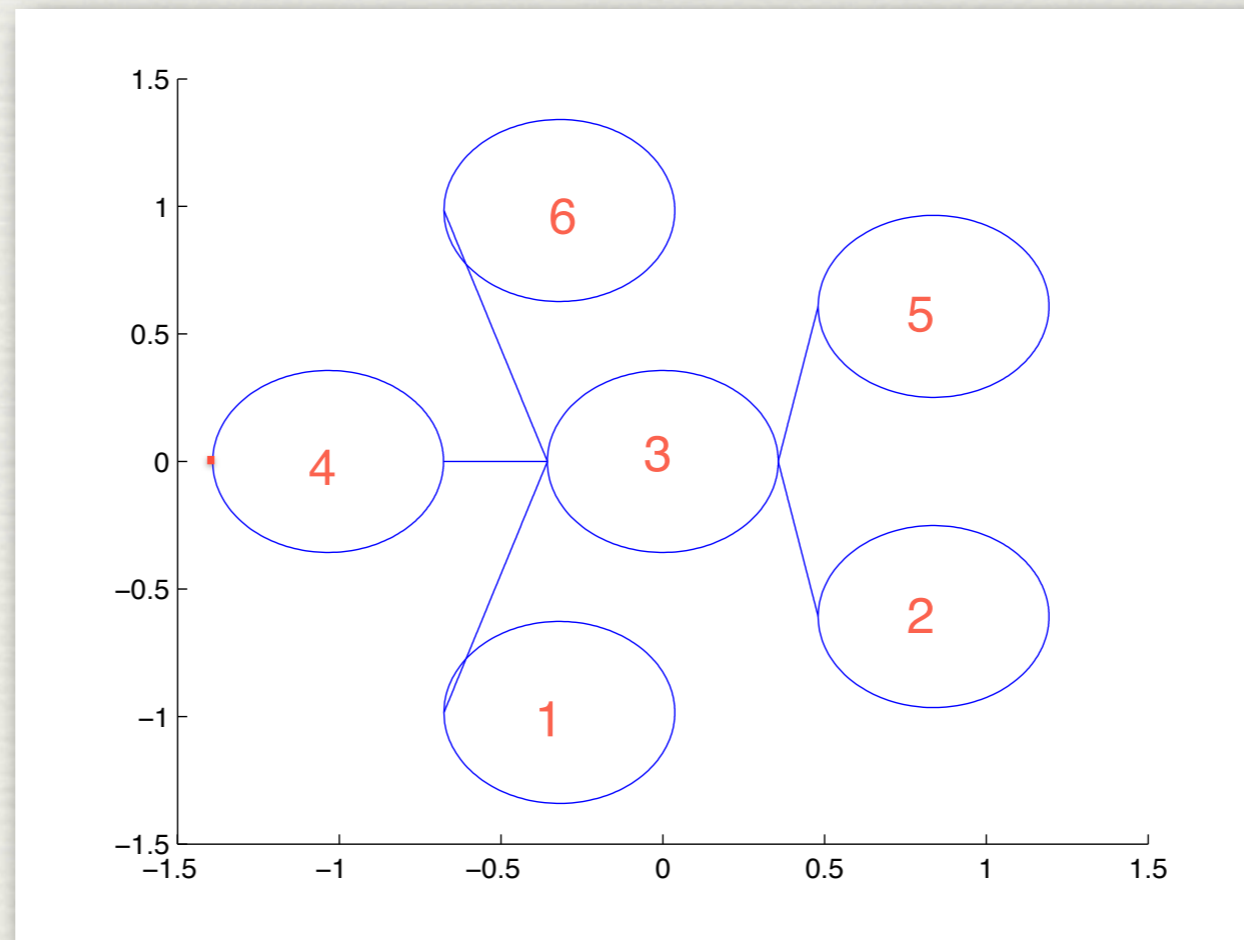
$$N_\theta > \frac{1}{2} + \sqrt{\frac{1}{4} - \frac{\ln \epsilon}{\pi \lambda_1}}$$

- symplectic transformation to Siegel fundamental domain (approximately) (Deconinck et al. 2002)



# Abel map

- ♦  $A(P)$ : determine closest marked point to  $P$ , analytic continuation of  $y$  from there and integration as before.
- ♦ critical points, infinity: substitution as indicated by Puiseux expansions





# Real Riemann surfaces

- ♦ in applications, solutions to PDEs in terms of theta functions must satisfy reality and smoothness conditions
- ♦ real Riemann surfaces: anti-holomorphic involution, convenient form of the homology basis
- ♦ smoothness: study of the theta divisor (zeros of the theta function) (Dubrovin, Natanzon, Vinnikov)



# Davey-Stewartson equations

$$i\psi_t + \psi_{xx} - \alpha^2 \psi_{yy} + 2(\Phi + \rho |\psi|^2) \psi = 0,$$

$$\alpha = i, 1, \quad \rho = \pm 1, \quad \Phi_{xx} + \alpha^2 \Phi_{yy} + 2\rho |\psi|_{xx}^2 = 0,$$

- ♦ model the evolution of weakly nonlinear water waves traveling predominantly in one direction, wave amplitude slowly modulated in two horizontal directions, plasma physics, ...
- ♦ completely integrable, theta-functional solutions (Malanyuk 1994, Kalla 2011)
- ♦ algorithm to transform computed homology basis to 'Vinnikov' basis (K, Kalla 2011)



# Trott curve

- M-curve,  $g = 3$ , real simple branch points ( $s = (1, -1, -1)$ )

$$144(x^4 + y^4) - 225(x^2 + y^2) + 350x^2y^2 + 81 = 0$$

$$\text{DS1}^+, \lambda(a) = -0.2, \lambda(b) = 0.2 \quad \alpha = i, \rho = 1$$

$$t \in [-2, 2]$$



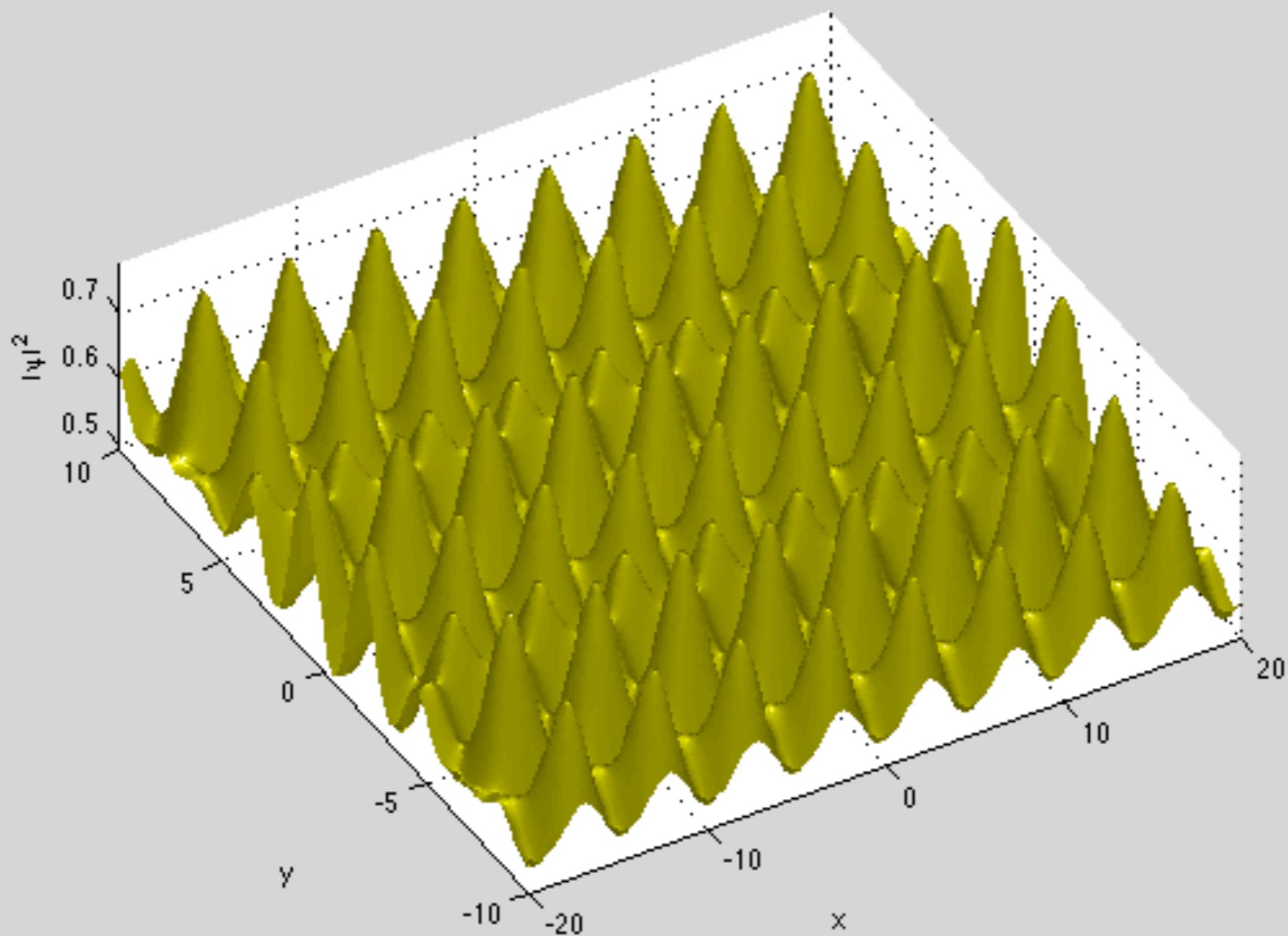
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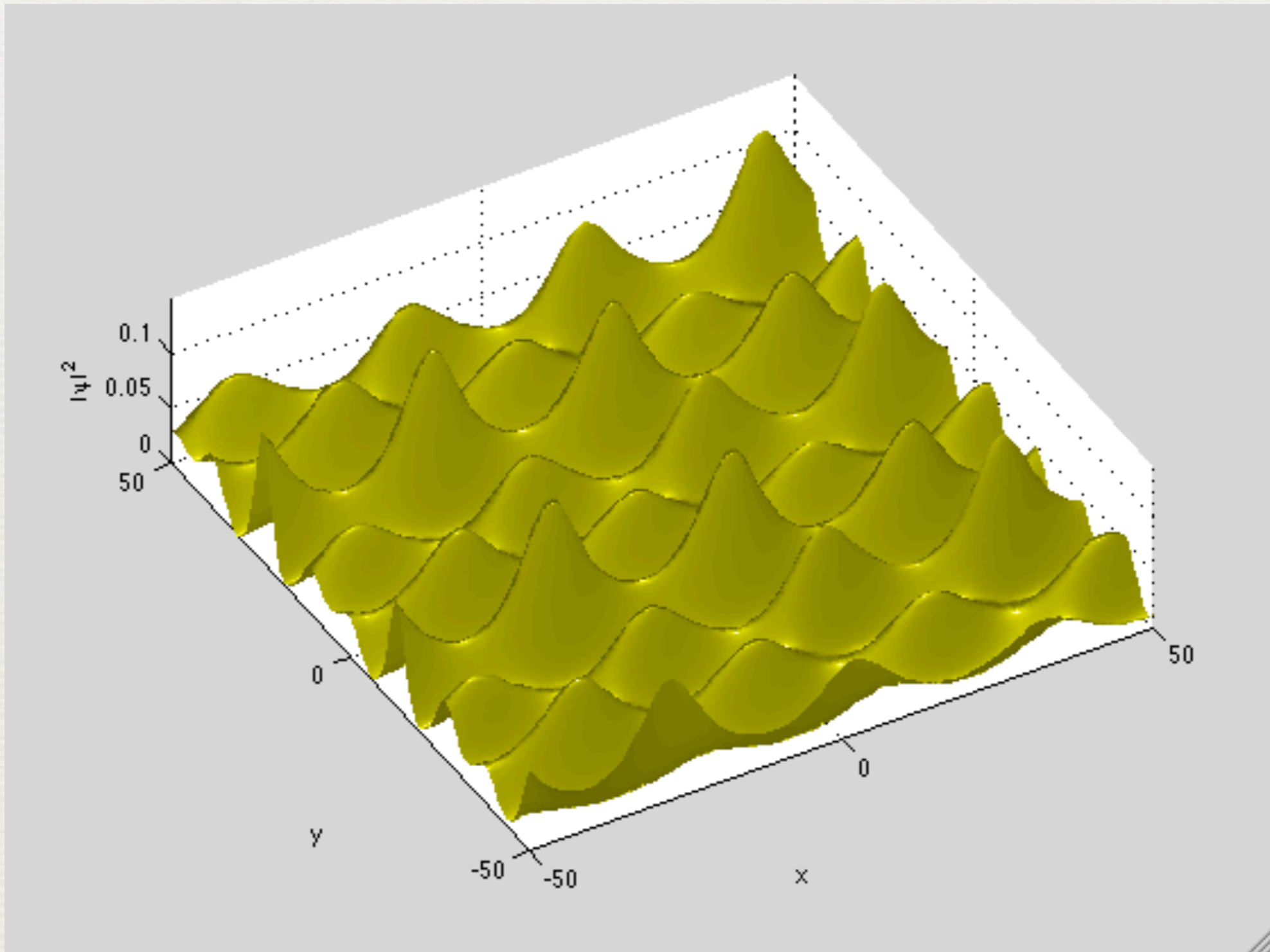
# DS on Fermat curve $g=3$

$$\text{DS2-}, \lambda(a) = -1.5 + i, \lambda(a) = -1.5 - i \quad t \in [-5, 5]$$



# DS on Fermat curve $g=3$

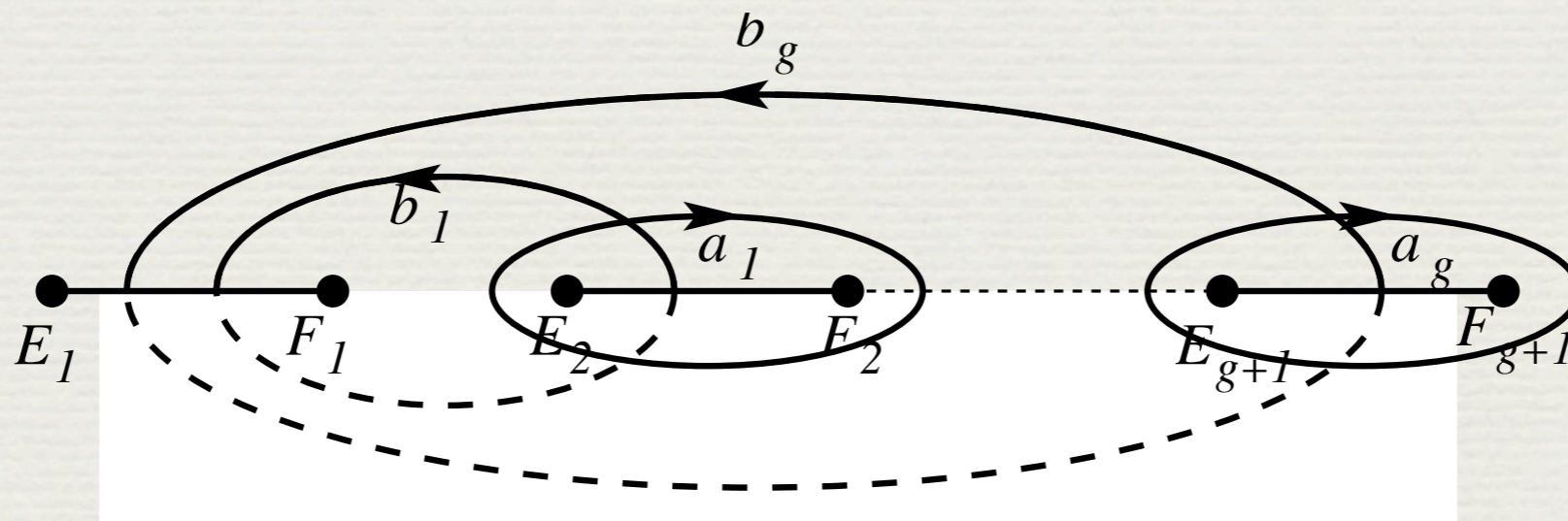
DS2-,  $\lambda(a) = -1.5 + i$ ,  $\lambda(a) = -1.5 - i$   $t \in [-5, 5]$





# Hyperelliptic surfaces

- ♦ general surface: analytic continuation most time consuming
- ♦  $y$ : square root of polynomial in  $x$ , holomorphic differentials known,  $y^2 + \prod_{i=1}^{2g+2} (x - x_i) = 0$
- ♦ analytic continuation of the root trivial (square root, correct unwanted sign changes)
- ♦ branch points prescribed, can almost collapse
- ♦ homology can be chosen a priori





# Outlook

- ♦ more efficient determination of critical points, homotopy tracing, endgame
- ♦ Abel map via Cauchy formula
- ♦ Siegel transformation of the Riemann matrix to fundamental domain
- ♦ parallelization of theta functions



# References

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